ANAND K SUBRAMANIAN

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WORK EXPERIENCE

Nov 2023 - Present	Machine Learning Engineer - Bodygram, Tokyo
	Developing Deep-Learning solutions for accurate human body measurement and un- derstanding. Technologies: Docker, Pytorch, PCL, Python
Feb 2022 - Nov 2023	Senior Computer Vision Engineer - DeepX Inc, Tokyo
	Developed Deep-Learning solutions for automating heavy construction vehicles like excavators and trucks. Worked predominantly on 3D computer vision, and point- clouds. Tasks include object detection, segmentation, tracking, and Sim2Real. Tech- nologies: ROS2, Docker, Pytorch, PCL, Python, C++
Oct 2019 - Jan 2022	Research Engineer - NABLAS Inc, Tokyo
	Successfully built and delivered Deep-Learning solutions for industrial anomaly detec- tion with real-world constraints. Tasks include zero-shot anomaly detection, acceler- ated distributed neural network training, and optimizing neural networks for efficient inference on NVIDIA edge-devices. Technologies: Docker, Pytorch, ONNX, Python
Feb 2019 - May 2019	Visiting Researcher - RIKEN-AIP, Tokyo
	Research Topic - Scaling up Gaussian Process using fast variational inference. Re- sponsible for implementing the code for the research topic and running various ex- periments. Technologies: TensorFlow, Python
Jul 2015 - Feb 2017	Project Associate - ADI DSP Lab, IIT Madras, India
	Developed low-cost ultra low-power prototypes for smart fire-alarm system (Patented and now commercialised). Responsible for circuit design, prototyping, and developing embedded DSP applications.
EDUCATION	
Oct 2017 - Dec 20	 Master's Degree in Information Science (MEXT Scholar) Japan Advanced Institute of Science and Technology (JAIST), Japan JAIST Best Outgoing Student Award 2019 JAIST President Award 2019 MEXT (文部科学省) Scholarship 2017 Thesis - Normalizing Deep Learning models for Embedded Robotics Publication - Mean Spectral Normalization of Deep Neural Networks for Embedded Automation. IEEE CASE 2019, doi: 10.1109/CASE.2019.8842955.
Aug 2011 - May 2	2015 Bachelor of Technology in Mechatronics Engineering

SRM University, India

First Class with Distinction - CGPA 8.89Thesis - Goal Searching algorithms for small robot swarms **Publication** -

Estimation of Optimum Robot Heading Using Savitzky-Golay and Kalman Filters. International Journal of Robotics and Automation. 1.2 (2016): 01-09. doi: 10.37628/ijra.v1i2.25